

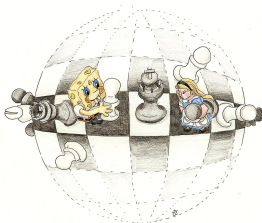
Need quantum entanglement? Don't sweat it, just pick at random!

Entangling quantum information theory and asymptotic geometric analysis

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- 1 Introduction
- 2 Tensor norms and entanglement
- 3 Typical amount of entanglement in random multipartite pure states
- 4 Typical amount of entanglement in more ‘physically relevant’ random multipartite pure states

What is quantum physics and why the need for it?

Quantum physics: theory that progressively arose to *explain certain observed physical phenomena*, which classical physics could not account for.

Examples of puzzling phenomena at the origin of the theory (in the 1900's):

- black-body radiation: resolved by *quantization* of light into photons (Planck, Einstein)
- electron interference: resolved by *wave function* description of particles (de Broglie, Schrödinger)

Full development of the theory from the 1920's (Heisenberg, Born, Dirac, Bohr, von Neumann, Bell, etc.)

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Some key aspects of quantum physics:

- Not needed to describe ordinary scale behaviors, only *very small scale* ones.
 - ↳ classical physics: approximation of quantum physics valid at macroscopic scale
- *Inherently probabilistic*, not just as a consequence of imprecisions or lack of knowledge.
 - ↳ even in ideal scenario, measurement outcomes cannot be predicted with certainty
- Neat mathematical formalism but *not so physically intuitive*.
 - ↳ striking consequences: uncertainty, superposition, entanglement, etc.

What is this talk about?

Goal of this talk: Explain how *asymptotic geometric analysis* can be useful to tackle problems arising in *quantum information theory*.

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Question 1: What is quantum information theory?

└→ communication, computation, encryption, etc.

Understanding if some *information processing tasks* could be performed more efficiently if the physical support of information obeys the laws of *quantum rather than classical physics*.

└→ e.g. electrons, photons

More specifically: Quantify the potential advantage of quantum over classical resources.

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Question 2: What is asymptotic geometric analysis?

Using *probabilistic techniques* to study *Banach spaces of finite but high dimension*.

What is this talk about? (continued)

Why “high dimension”? $\hookrightarrow$ 2-level quantum system (e.g. electron's spin, photon's polarization)

Quantum system composed of 1 qubit: described by the space $\mathbf{C}^2$.

Quantum system composed of M qubits: described by the space $(\mathbf{C}^2)^{\otimes M} \equiv \mathbf{C}^{2^M}$.

$\longrightarrow$ The dimension of a system *grows exponentially* with its number of subsystems, so we have to deal with high dimension as soon as more than a few qubits are involved.

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Why “probabilistic techniques”?

- 1 Identify the *typical properties of quantum systems*, i.e. when they are picked at random.
- 2 Prove the *existence of quantum systems having certain properties*, using random constructions.

Note: “typical” = “with probability going to 1 as the underlying dimension grows”.

$\rightarrow$ There are usually two steps in the argument:

- 1 Identify the average behavior of the property under consideration.
- 2 Show that this average behavior is generic in high dimension.

Concentration of measure phenomenon: a sufficiently ‘well-behaved’ many-variable function has a very small probability of deviating from its average.

Mathematical formalism of quantum physics in a nutshell

- Quantum system composed of 1 subsystem: Complex Hilbert space H .
→ Finite-dimensional case: $H \equiv \mathbf{C}^d$ for some $d \in \mathbf{N}$ (equipped with inner product $\langle \cdot | \cdot \rangle$).

Quantum system composed of M subsystems: Complex Hilbert space $H = H_1 \otimes \cdots \otimes H_M$, tensor product of the complex Hilbert spaces corresponding to each subsystem.

→ Finite-dimensional case: for each $1 \leq i \leq M$, $H_i \equiv \mathbf{C}^{d_i}$ for some $d_i \in \mathbf{N}$, so $H \equiv \mathbf{C}^{d_1 \cdots d_M}$.

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- State of system H :

Pure state: unit vector ψ in H (or rather associated rank 1 projector $\psi\psi^*$ on H).

Mixed state: convex combination of pure states

$$\rho = \sum_{k=1}^r \mu_k \psi_k \psi_k^*, \text{ with } \begin{cases} \mu_1, \dots, \mu_r \geq 0, \sum_{k=1}^r \mu_k = 1 \\ \psi_1, \dots, \psi_r \text{ unit vectors in } H \end{cases}.$$

Equivalently, ρ is a self-adjoint positive semidefinite and trace 1 operator on H .

→ Finite-dimensional case: $\rho \in \mathcal{M}_d(\mathbf{C})$ s.t. $\rho^* = \rho$, $\rho \geq 0$ and $\text{Tr}(\rho) = 1$.

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Classical-Quantum correspondence:

Given a quantum state $\rho \in \mathcal{M}_d(\mathbf{C})$, $\text{spec}(\rho) \in \mathbf{R}^d$ is a probability vector, i.e. a classical state.

Extra freedom: choice of basis where ρ is diagonal.

Separability vs entanglement in multipartite quantum systems

Definition [Separability and entanglement]

A state ρ on $H_1 \otimes \cdots \otimes H_M$ is called *separable* if it is a convex combination of product states, i.e.

↳ self-adjoint positive semidefinite operator with trace 1 on $H_1 \otimes \cdots \otimes H_M$

$$\rho = \sum_{k=1}^r \mu_k \rho_1^k \otimes \cdots \otimes \rho_M^k, \text{ with } \begin{cases} \mu_1, \dots, \mu_r \geq 0, \sum_{k=1}^r \mu_k = 1 \\ \rho_i^1, \dots, \rho_i^r \text{ states on } H_i, \text{ for each } 1 \leq i \leq M \end{cases} .$$

Otherwise it is called *entangled*.

[Note: If ρ is a pure state, i.e. $\rho = \psi\psi^*$ for some unit vector $\psi \in H_1 \otimes \cdots \otimes H_M$, then ρ is separable iff $\psi = \psi_1 \otimes \cdots \otimes \psi_M$ for some unit vectors $\psi_i \in H_i$, for each $1 \leq i \leq M$.]

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Observation:

- In a *product state*, there are *no correlations* between subsystems.
↳ $\rho = \rho_1 \otimes \cdots \otimes \rho_M$ ↳ cf. independent random variables: joint distribution factorizes
- In a *separable state*, there are only *classical correlations* between subsystems.
↳ $\rho = \sum_{k=1}^r \mu_k \rho_1^k \otimes \cdots \otimes \rho_M^k$ ↳ described by the probability distribution $\mu = (\mu_1, \dots, \mu_r)$
- In an *entangled state*, there are *intrinsically quantum correlations* between subsystems.

Fact: In most information processing tasks, a quantum system must be in an entangled state to provide an advantage over a classical system.

→ *Certifying entanglement* (and quantifying it) is an important issue in practice.

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Tensor norms in Banach spaces

Let $A_1, \dots, A_M$ be Banach spaces. Given $x \in A_1 \otimes \dots \otimes A_M$, its *injective norm* is

$$\|x\|_{A_1 \otimes_{\varepsilon} \dots \otimes_{\varepsilon} A_M} := \sup \{ |\langle b_1 \otimes \dots \otimes b_M | x \rangle| : b_i \in A_i^*, \|b_i\|_{A_i^*} \leq 1 \},$$

and its *projective norm* is

$$\|x\|_{A_1 \otimes_{\pi} \dots \otimes_{\pi} A_M} := \inf \left\{ \sum_{k=1}^r |\alpha_k| : a_i^k \in A_i, \|a_i^k\|_{A_i} \leq 1, x = \sum_{k=1}^r \alpha_k a_1^k \otimes \dots \otimes a_M^k, r \in \mathbf{N} \right\}.$$

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These norms are dual to one another: for all $x \in A_1 \otimes \dots \otimes A_M$,

$$\|x\|_{A_1 \otimes_{\varepsilon} \dots \otimes_{\varepsilon} A_M} = \sup \{ |\langle y | x \rangle| : \|y\|_{A_1^* \otimes_{\pi} \dots \otimes_{\pi} A_M^*} \leq 1 \},$$

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The injective and projective norms are examples of *tensor norms*: for all $a_1 \in A_1, \dots, a_M \in A_M$,

$$\|a_1 \otimes \dots \otimes a_M\|_{A_1 \otimes_{\varepsilon} \dots \otimes_{\varepsilon} A_M} = \|a_1 \otimes \dots \otimes a_M\|_{A_1 \otimes_{\pi} \dots \otimes_{\pi} A_M} = \|a_1\|_{A_1} \dots \|a_M\|_{A_M}.$$

And they are *extremal* among such norms: for any other tensor norm $\|\cdot\|$ on $A_1 \otimes \dots \otimes A_M$,

$$\|\cdot\|_{A_1 \otimes_{\varepsilon} \dots \otimes_{\varepsilon} A_M} \leq \|\cdot\| \leq \|\cdot\|_{A_1 \otimes_{\pi} \dots \otimes_{\pi} A_M}.$$

Characterizing entanglement through tensor norms

• Pure state entanglement:

Banach spaces $(\mathbf{C}^{d_i}, \|\cdot\|_{\ell_2^{d_i}})$, $1 \leq i \leq M$. [Notation: $\forall x \in \mathbf{C}^d$, $\|x\|_{\ell_2^d} := (\sum_{k=1}^d |x_k|^2)^{1/2}$] ↗ vector 2-norm

because $\|\cdot\|_{\ell_2^{d_1 \cdots d_M}}$ is a tensor norm ← ↙
 A pure state $\psi \in \mathbf{C}^{d_1} \otimes \cdots \otimes \mathbf{C}^{d_M}$ is s.t. $\|\psi\|_{\ell_2^{d_1 \cdots d_M}} = 1$, and thus $\begin{cases} \|\psi\|_{\ell_2^{d_1} \otimes_\epsilon \cdots \otimes_\epsilon \ell_2^{d_M}} \leq 1 \\ \|\psi\|_{\ell_2^{d_1} \otimes_\pi \cdots \otimes_\pi \ell_2^{d_M}} \geq 1 \end{cases}$.

And ψ is separable iff $\|\psi\|_{\ell_2^{d_1} \otimes_\epsilon \cdots \otimes_\epsilon \ell_2^{d_M}} = \|\psi\|_{\ell_2^{d_1} \otimes_\pi \cdots \otimes_\pi \ell_2^{d_M}} = 1$.

Reminder: $\|\psi\|_{\ell_2^{d_1} \otimes_\epsilon \cdots \otimes_\epsilon \ell_2^{d_M}} := \sup \left\{ |\langle \varphi_1 \otimes \cdots \otimes \varphi_M | \psi \rangle| : \varphi_i \in \mathbf{C}^{d_i}, \|\varphi_i\|_{\ell_2^{d_i}} = 1 \right\}$
 $\|\psi\|_{\ell_2^{d_1} \otimes_\pi \cdots \otimes_\pi \ell_2^{d_M}} := \inf \left\{ \sum_{k=1}^r |\alpha_k| : \chi_i^k \in \mathbf{C}^{d_i}, \|\chi_i^k\|_{\ell_2^{d_i}} = 1, \psi = \sum_{k=1}^r \alpha_k \chi_1^k \otimes \cdots \otimes \chi_M^k \right\}$

Quantifying entanglement through tensor norms (physical point of view)

If $\|\psi\|_{\ell_2^{d_1} \otimes_\epsilon \dots \otimes_\epsilon \ell_2^{d_M}} \ll 1$ or $\|\psi\|_{\ell_2^{d_1} \otimes_\pi \dots \otimes_\pi \ell_2^{d_M}} \gg 1$, then ψ is 'very' entangled.

If $\|\rho\|_{S_1^{d_1} \otimes_\pi \dots \otimes_\pi S_1^{d_M}} \gg 1$, then ρ is 'very' entangled.

Questions: Can this be made *quantitative*?

Is there an *operational interpretation* for these norms being 'small' or 'large'?

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Definition [Geometric measure of entanglement (Wei/Goldbart)]

Let $\psi \in H_1 \otimes \dots \otimes H_M$ be a pure state. Its *geometric measure of entanglement (GME)* is

$$E(\psi) := -\log \sup \left\{ |\langle \phi_1 \otimes \dots \otimes \phi_M | \psi \rangle|^2 : \phi_i \in H_i, \|\phi_i\|_{\ell_2^{d_i}} = 1 \right\} = -2 \log \|\psi\|_{\ell_2^{d_1} \otimes_\epsilon \dots \otimes_\epsilon \ell_2^{d_M}}.$$

Fact: The GME has a meaning in several quantum information processing tasks (construction of *entanglement witnesses*, *discrimination of quantum states* under local operations, detection of *phase transition* in quantum many-body systems, etc.)

From the definition, $E(\psi) = 0$ iff ψ is separable. But how large can $E(\psi)$ be for ψ entangled?

↳ *faithful entanglement measure* for multipartite pure states

Quantifying entanglement through tensor norms (mathematical point of view)

Let us look at the previous definitions in the case of pure states for $M = 2$ and $H_1 \equiv H_2 \equiv \mathbf{C}^d$.

We can identify $x = \sum_{k,l=1}^d x_{kl} e_k \otimes e_l \in \mathbf{C}^d \otimes \mathbf{C}^d$ with $X = \sum_{k,l=1}^d x_{kl} e_k e_l^* \in \mathcal{M}_d(\mathbf{C})$.

The *singular value decomposition* of X thus corresponds to the *Schmidt decomposition* of x :

$$X = \sum_{k=1}^r s_k u_k v_k^* \longleftrightarrow x = \sum_{k=1}^r s_k u_k \otimes v_k, \text{ with } r \leq d \text{ and } \begin{cases} s_1, \dots, s_r > 0 \\ \{u_k\}_{k=1}^r, \{v_k\}_{k=1}^r \text{ o.n.f. in } \mathbf{C}^d \end{cases}.$$

This identification preserves the Euclidean norm: $\|x\|_{\ell_2^{d^2}} = (\sum_{k=1}^r s_k^2)^{1/2} = \|X\|_{S_2^d}$.

While $\|x\|_{\ell_2^d \otimes_\epsilon \ell_2^d} = \max_{1 \leq k \leq r} s_k = \|X\|_{S_\infty^d}$ and $\|x\|_{\ell_2^d \otimes_\pi \ell_2^d} = \sum_{k=1}^r s_k = \|X\|_{S_1^d}$.

→ If $\|x\|_{\ell_2^{d^2}} = 1$, then by Cauchy-Schwarz $\frac{1}{\sqrt{d}} \leq \|x\|_{\ell_2^d \otimes_\epsilon \ell_2^d} \leq 1$ and $1 \leq \|x\|_{\ell_2^d \otimes_\pi \ell_2^d} \leq \sqrt{d}$.
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More generally: Assume that $d_1 \leq \dots \leq d_M$ and set $D := d_1 \times \dots \times d_{M-1}$.

- For any pure state $\psi \in \mathbf{C}^{d_1} \otimes \dots \otimes \mathbf{C}^{d_M}$, $\|\psi\|_{\ell_2^{d_1} \otimes_{\varepsilon} \dots \otimes_{\varepsilon} \ell_2^{d_M}} \geq \frac{1}{\sqrt{D}}$ and $\|\psi\|_{\ell_2^{d_1} \otimes_{\pi} \dots \otimes_{\pi} \ell_2^{d_M}} \leq \sqrt{D}$.

Proof idea: Recursive argument from bipartite case.

- For any mixed state $\rho \in \mathcal{M}_{d_1}(\mathbf{C}) \otimes \dots \otimes \mathcal{M}_{d_M}(\mathbf{C})$, $\|\rho\|_{S_1^{d_1} \otimes_{\pi} \dots \otimes_{\pi} S_1^{d_M}} \leq D$.

Proof idea: Pure states are extremal and $\|\psi\psi^*\|_{S_1^{d_1} \otimes_{\pi} \dots \otimes_{\pi} S_1^{d_M}} = \|\psi\|_{\ell_2^{d_1} \otimes_{\pi} \dots \otimes_{\pi} \ell_2^{d_M}}^2$.

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Entanglement of uniformly distributed multipartite pure states

[Notation from now on: $\|\cdot\| := \|\cdot\|_{\ell_2^n}$, $\|\cdot\|_{\varepsilon} := \|\cdot\|_{(\ell_2^d)^{\otimes_{\varepsilon} M}}$, $\|\cdot\|_{\pi} := \|\cdot\|_{(\ell_2^d)^{\otimes_{\pi} M}}$.]

Fact: For any unit vector $\psi \in (\mathbf{C}^d)^{\otimes M}$, $\|\psi\|_{\varepsilon} \geq \frac{1}{\sqrt{d^{M-1}}}$, i.e. $E(\psi) \leq (M-1) \log d$.

Question: Are multipartite pure states generically ‘very’ or ‘little’ entangled?

→ For a unit vector $\psi \in (\mathbf{C}^d)^{\otimes M}$ sampled at random, what is typically the value of $\|\psi\|_{\varepsilon}$, and thus of $E(\psi)$?

Entanglement of uniformly distributed multipartite pure states

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Theorem [Typical injective norm of a uniformly distributed unit vector (Aubrun/Szarek)]

There exist constants $c, C, c_0 > 0$ s.t., for $\psi \in (\mathbf{C}^d)^{\otimes M}$ a uniformly distributed unit vector,
↳ i.e. $U\psi \sim \psi$ for all unitary U on $(\mathbf{C}^d)^{\otimes M}$

$$\mathbf{P} \left(c \sqrt{\frac{M \log M}{d^{M-1}}} \leq \|\psi\|_\varepsilon \leq C \sqrt{\frac{M \log M}{d^{M-1}}} \right) \geq 1 - e^{-c_0 d M \log M}.$$

Consequence: For $\psi \in (\mathbf{C}^d)^{\otimes M}$ a uniformly distributed pure state, when d is large, $E(\psi) = (M-1) \log d - \log(M \log M) + O(1)$ with high probability.

→ Such random multipartite pure states are typically close to maximally entangled.

In fact, for $M > 2$, there are no explicit examples of so highly entangled multipartite pure states!

Main tools in the proof

Observation: A uniformly distributed unit vector $\psi \in (\mathbf{C}^d)^{\otimes M}$ has the same distribution as $g/\|g\|$, where $g \in (\mathbf{C}^d)^{\otimes M}$ is a Gaussian vector.

↳ independent complex Gaussian entries with mean 0 and variance 1

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• Estimating the supremum of a Gaussian process:

Given $K \subset \mathbf{C}^n$ a subset of the unit sphere, we want to estimate $\mathbf{E} \sup_{x \in K} |\langle x | g \rangle|$.

Definitions: $C_\delta \subset K$ is a δ -covering set if: $\forall x \in K, \exists y \in C_\delta : \|x - y\| \leq \delta$.

$S_\delta \subset K$ is a δ -separated set if: $\forall x, y \in S_\delta, x \neq y \Rightarrow \|x - y\| \geq \delta$.

Fact: Upper bound: $\mathbf{E} \sup_{x \in K} |\langle x | g \rangle| \leq \frac{1}{1-\delta} \mathbf{E} \sup_{x \in C_\delta} |\langle x | g \rangle| \leq \frac{1}{1-\delta} \sqrt{2 \log |C_\delta|}$
discretization argument ↙ ↘ 'baby' chaining argument

Lower bound: $\mathbf{E} \sup_{x \in K} |\langle x | g \rangle| \geq \mathbf{E} \sup_{x \in S_\delta} |\langle x | g \rangle| \geq \delta \sqrt{\frac{\log |S_\delta|}{2\pi \log 2}}$
Sudakov inequality ↙

→ Taking $K := \{\varphi_1 \otimes \cdots \otimes \varphi_M : \varphi_i \in \mathbf{C}^d, \|\varphi_i\| = 1\}$, we have $\mathbf{E} \|g\|_\epsilon = \mathbf{E} \sup_{\varphi \in K} |\langle \varphi | g \rangle|$.

Main tools in the proof

Observation: A uniformly distributed unit vector $\psi \in (\mathbf{C}^d)^{\otimes M}$ has the same distribution as $g/\|g\|$, where $g \in (\mathbf{C}^d)^{\otimes M}$ is a Gaussian vector.

↳ independent complex Gaussian entries with mean 0 and variance 1

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• Gaussian concentration inequality:

Given $f : \mathbf{C}^n \rightarrow \mathbf{R}$ an L -Lipschitz function, we have: $\forall \varepsilon > 0, \mathbf{P}(f(g) \geq \mathbf{E} f \pm \varepsilon) \leq e^{-\varepsilon^2/L^2}$.

→ Taking $f := \|\cdot\|_\varepsilon$, f is 1-Lipschitz.

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Questions:

- 1 Can we exhibit so highly entangled states with constructions that require less randomness? or even explicit ones?
- 2 The uniform distribution might not capture truly 'interesting' states... What about estimating the typical entanglement of more 'physically relevant' states?

- 1 Introduction
- 2 Tensor norms and entanglement
- 3 Typical amount of entanglement in random multipartite pure states
- 4 Typical amount of entanglement in more 'physically relevant' random multipartite pure states**

The curse of dimensionality when dealing with many-body quantum systems

Main issue when dealing with many-body quantum systems: exponential growth of the dimension. However, 'physically relevant' states of such systems are often well approximated by so-called *tensor network states (TNS)*, which form a small subset of the global state space.

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Example: A *matrix product state (MPS)* on $(\mathbf{C}^d)^{\otimes M}$ is a pure state $\psi \in (\mathbf{C}^d)^{\otimes M}$ of the form

$$\psi = \sum_{k_1, \dots, k_M=1}^d \text{Tr} \left(X_{k_1}^{(1)} \cdots X_{k_M}^{(M)} \right) e_{k_1} \otimes \cdots \otimes e_{k_M}, \text{ where } X_1^{(i)}, \dots, X_d^{(i)} \in \mathcal{M}_q(\mathbf{C}), 1 \leq i \leq M.$$

→ Such state is described by Mdq^2 parameters, which is linear rather than exponential in M .

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Fact: On a 1D system (M subsystems disposed on a line), the *ground state of a gapped local Hamiltonian* is well approximated by an MPS (Hastings, Landau/Vazirani/Vidick)

spectral gap lower bounded by a constant independent of M ←

composed of terms which act non-trivially only on nearby sites ←

→ In condensed-matter physics, MPS are used as Ansatz in ground energy computations: optimization over a manageable number of parameters, even for large M .

Entanglement of random MPS

→ independent complex Gaussian entries with mean 0 and variance 1

Idea: Pick $X_1^{(i)}, \dots, X_d^{(i)} \in \mathcal{M}_q(\mathbf{C})$, $1 \leq i \leq M$, independent Gaussian matrices.

Let $\psi \in (\mathbf{C}^d)^{\otimes M}$ be the corresponding random MPS, i.e.

$$\psi = \frac{\psi'}{\|\psi'\|} \text{ with } \psi' = \sum_{k_1, \dots, k_M=1}^d \text{Tr} \left(X_{k_1}^{(1)} \dots X_{k_M}^{(M)} \right) e_{k_1} \otimes \dots \otimes e_{k_M}.$$

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Remark: The parameter q quantifies the amount of bipartite entanglement: across any splitting of subsystems $\{1, \dots, L\}$ vs $\{L+1, \dots, M\}$, ψ has Schmidt rank at most $q^2 \ll d^L$.

→ area vs volume law

Now what about genuinely multipartite entanglement?

→ If $q = 1$, $\psi = \psi_1 \otimes \cdots \otimes \psi_M$ is separable. But what can we say for $q \gg 1$?

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Result: For $\psi \in (\mathbf{C}^d)^{\otimes M}$ a Gaussian MPS with bond dimension q , when d and q are large, $E(\psi) = (M-1) \log \min(d, q) + O(1)$ with high probability (Fitter/Lancien/Nechita).

→ Such random multipartite pure states have an amount of entanglement which is not maximal if $q \ll d$, but still extensive.

Proof idea: Estimate $\mathbf{E} \|\psi\|_\varepsilon$ with a discretization argument and bound the probability of deviating from it with a local version of the Gaussian concentration inequality.

- Can we estimate the injective norm for *other models of random multipartite pure states*?

→ Trade-off between ‘mathematically tractable’ and ‘physically relevant’...!

on regular lattice or more complicated graph ↙

E.g. 2D or 3D ground states are also well-approximated by tensor network states.

→ Some of their typical entanglement-related properties have been studied: *correlations* (Lancien/Pérez-García), *mutual information* (Hayden/Nezami/Qi/Thomas/Walter/Yang), etc.

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- What about computing *projective norms* rather than injective norms?

This would be particularly useful for quantifying the entanglement of mixed multipartite states, which is in general a *hard problem* (Gharibian, Pérez-García).

For pure states, we at least have a lower bound (by duality): $\|\psi\|_{\pi} \geq \frac{1}{\|\psi\|_{\varepsilon}}$.

For mixed states, we can define *sufficient conditions for entanglement*, which consist in checking pure state entanglement (Jivulescu/Lancien/Nechita).

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